

Pandora's Box with Correlations: Learning and Approximation

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A Search Problem

Find the best out of n alternatives!



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- ▶ Stochastic information on price

A Search Problem

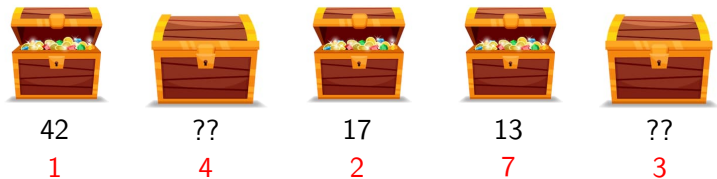
Find the best out of n alternatives!



- ▶ Stochastic information on price
- ▶ Information is not free!

A Search Problem

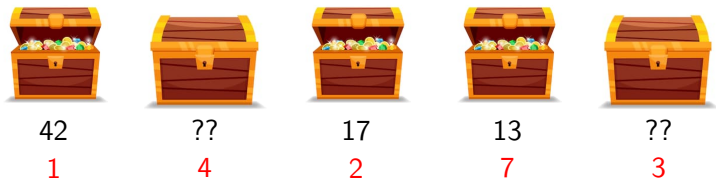
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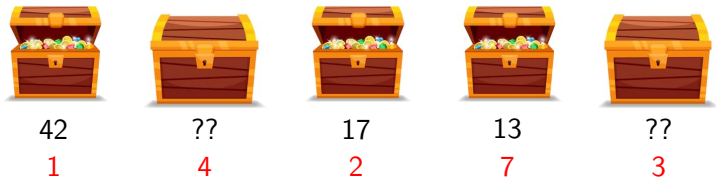


- ▶ Stochastic information on price
- ▶ **Information is not free!**
- ▶ Open boxes until decide to stop (*stopping rule*).
- ▶ Keep best price seen so far

Instantiation of prices = *scenario*

A Search Problem

Find the best out of n alternatives!



- ▶ Stochastic information on price
- ▶ **Information is not free!**

Maximization version: *max price - information cost*

Minimization version: *min price + information cost*

This paper: focus on minimization

A Search Problem - What do we know

Pandora's Box [Weitzman '79] greedy gives optimal!

- ▶ Assign an index to every box
- ▶ Search boxes in order of index until: current price better than index of next box

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Crucial assumption: distributions are **independent!**

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Our setting: sample access, arbitrarily correlated \mathcal{D} 's

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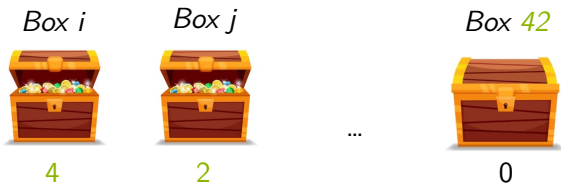
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Related but different: Optimal Decision Tree (require small support/explicit distributions)

Approximating the Optimal

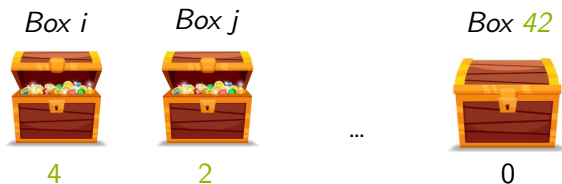
Hard Problem: encode location of best box in prices of other boxes



Example: prices 4 and 2 means go to box 42 to find best price

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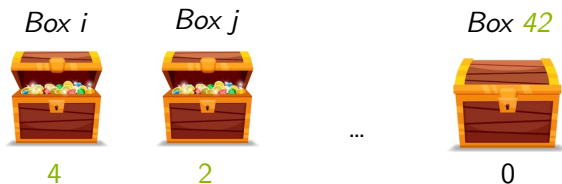


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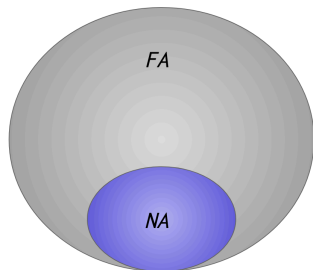
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Best Strategy: decide next box after seen prices. Other strategies?

Strategies

Strategy: (1) What is next box? (2) When do I stop?

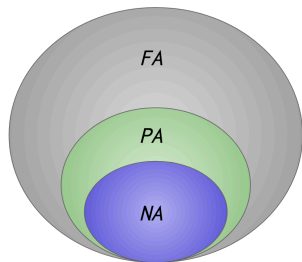
- ▶ *Fully Adaptive*: next box/stopping rule **both** adaptive
- ▶ *Non-Adaptive*: fixed order **and** stopping time
Fixed stopping time: fix a set of boxes to open all at once, decide which to pick



Strategies

Strategy: (1) What is next box? (2) When do I stop?

- ▶ *Partially Adaptive*: fixed order, adaptive stopping time (for independent \mathcal{D} this gives optimal policy!)



Approximating Other Strategies

- ▶ **Fully Adaptive:** Learning/Approximation: Hard!
Example: encoded location of best box
- ▶ **Non-Adaptive:**
 - ▶ **Learning: Hard!**: tiny probability scenario has price= ∞ on all boxes but one \rightarrow either query all boxes **or** sample this scenario
 - ▶ **Approximation: As hard as Set Cover!** For $0/\infty$ prices \rightarrow find a 0 for every scenario \rightarrow hitting set formulation of set cover
- ▶ **Partially Adaptive:** Can Learn & Efficiently approximate!

Main Theorem

Using polynomially in n sampled scenarios we can efficiently find a Partially Adaptive strategy that is $O(1)$ -competitive against the optimal Partially Adaptive strategy.

Roadmap to Main Result

Space of PA strategies can be **large!** → **Scenario-aware PA**

SPA: Fix order → scenario is revealed → decide stopping time

Algorithm:

1. Draw samples of scenarios
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3. Find stopping rule that performs well (**Myopic Stopping Lemma**)

Roadmap to Main Result

Algorithm:

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Lemma (Myopic Stopping)

For any order, there is an adaptive stopping rule that 2-approximates the optimal Scenario-aware stopping rule.

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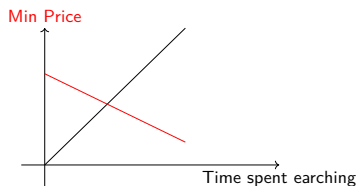
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Lemma (Myopic Stopping)

For any order, there is an adaptive stopping rule that 2-approximates the optimal Scenario-aware stopping rule.

Proof Sketch: Assume a SPA order \rightarrow need to find a stopping rule for PA. Stop when best price seen so far is at most time spent until now^a.



^aArgument is equivalent to Ski-Rental \rightarrow can get 1.58 using ski rental algorithm.

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Lemma (Myopic Stopping)

For any order, there is an adaptive stopping rule that 2-approximates the optimal Scenario-aware stopping rule.

Focus on SPA then convert to PA losing a factor of 2.

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Lemma

Near-Optimal SPA Strategies can be efficiently learned from $\text{poly}(n)$ number of samples.

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Proof Sketch.

Possible permutations: $n!$

Each permutation has bounded cost \rightarrow can learn with few samples \rightarrow union bound on all $n!$ permutations. □

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Lemma

Near-Optimal SPA Strategies can be efficiently learned from $\text{poly}(n)$ number of samples.

Enough to find good SPA strategies!

Roadmap to Main Result

Algorithm:

1. Draw samples of scenarios (Learning Lemma)
2. **Design good SPA strategy using samples (Main Algorithm)**
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Main Result: SPA vs PA

This talk: Focus on SPA vs NA

PA vs NA - LP Formulation

$$\begin{aligned} \text{minimize} \quad & \sum_{i \in \mathcal{B}} x_i + \frac{1}{|\mathcal{S}|} \sum_{i \in \mathcal{B}, s \in \mathcal{S}} c_{is} z_{is} && \text{(LP-NA)} \\ \text{subject to} \quad & \sum_{i \in \mathcal{B}} z_{is} = 1, && \forall s \in \mathcal{S} \quad (1) \\ & z_{is} \leq x_i, && \forall i \in \mathcal{B}, s \in \mathcal{S} \\ & x_i, z_{is} \in [0, 1] && \forall i \in \mathcal{B}, s \in \mathcal{S} \end{aligned}$$

x_i : indicates whether box i is opened

z_{is} : indicates whether box i is assigned to scenario s

c_{is} : price in box i for scenario s

PA vs NA - Algorithm

Given: Solution \mathbf{x}, \mathbf{z} to LP, scenario s

1. Open box i w.p. $\frac{x_i}{\sum_{i \in \mathcal{B}} x_i}$
2. If box i is opened, select the box and stop w.p. $\frac{z_{is}}{x_i}$

Analysis: Bound probing cost + price

- ▶ Part 1: bound probing cost

$$\Pr[\text{stop at step } t] = \sum_{i \in \mathcal{B}} \frac{x_i}{\sum_{i \in \mathcal{B}} x_i} \frac{z_{is}}{x_i} = \frac{\sum_{i \in \mathcal{B}} z_{is}}{\sum_{i \in \mathcal{B}} x_i} = \frac{1}{\text{OPT}_t},$$

Probing cost is optimal on expectation

PA vs NA - Analysis

- ▶ Part 2: bound the price
For scenario s

$$\begin{aligned}\mathbf{E}[\text{ALG}_{c,s}] &= \sum_{i \in \mathcal{B}, t} \mathbf{Pr}[\text{select } i \text{ at } t \mid \text{stop at } t] \mathbf{Pr}[\text{stop at } t] c_{is} \\ &\leq \sum_{i \in \mathcal{B}, t} \frac{z_{is}}{\sum_{i \in \mathcal{B}} z_{is}} \mathbf{Pr}[\text{stop at } t] c_{is} \\ &= \sum_{i \in \mathcal{B}} z_{is} c_{is} \\ &= \text{OPT}_{c,s}\end{aligned}$$

Take expectation over all scenarios $\mathbf{E}[\text{ALG}_c] \leq \text{OPT}_c$

SPA Approximates NA \rightarrow lose a 2-factor to convert to PA

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Showed: Can approximate NA with PA within 2.

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	Choose 1	Choose k	Matroid rank k
PA vs PA (Upper-bound)	9.22	$O(1)$	$O(\log k)$
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Maximization: Cannot approximate the Non-Adaptive using a Fully Adaptive within any constant.

Future directions

Our work: tradeoff adaptivity vs computational complexity

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- ▶ What can we approximate by fully adaptive strategies?
- ▶ Can we get adaptive algorithms for more general combinatorial problems?

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Thank you!